

# English and L<sup>A</sup>T<sub>E</sub>X for Mathematicians

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# Outline

Last week: Giving Presentations

This week: posters in  $X_{\text{3}}\text{L}^{\text{A}}\text{T}_{\text{E}}\text{X}$

2. Structure of a paper

Next: More about writing math



# Structuring research papers

0. Abstract
1. Introduction
2. Preliminaries
3. ⟨Main theorem⟩
4. further material (optional)
99. References



# Formulating definitions and theorems

- full sentences,
- all preliminaries,
- check whether claim correct



## Example: Definition

### Definition

A Lie algebra is a vector space  $\mathfrak{g}$  together with a bilinear skew-symmetric operation  $[\cdot, \cdot]: \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$  subject to the Jacobi identity

$$[X, [Y, Z]] + [Y, [Z, X]] + [Z, [X, Y]] = 0$$

for all  $X, Y, Z \in \mathfrak{g}$ .

### Proposition

A vector subspace  $\mathfrak{h} \subset \mathfrak{g}$  of a Lie algebra  $(\mathfrak{g}, [\cdot, \cdot])$  is a Lie subalgebra iff the bracket closes on  $\mathfrak{h}$ , i.e.  $[\mathfrak{h}, \mathfrak{h}] \subset \mathfrak{h}$ .



## Example: Theorem

### Definition

*A Lie algebra  $\mathfrak{g}$  is said to be semi-simple iff  $[\mathfrak{g}, \mathfrak{g}] = \mathfrak{g}$ .*

*A vector subspace  $I \subset \mathfrak{g}$  is called ideal iff  $[I, \mathfrak{g}] \subset I$ .*

*A Lie algebra is said to be simple iff it has no (nontrivial) ideals.*

### Theorem (Krull–Schmidt)

*A finite dimensional semi-simple Lie algebra is the direct sum of simple Lie subalgebras.*



## Formulating examples

### Example (Lie algebras)

1. The real space  $\mathbb{R}^3$  together with the vector product  $\times$ , defined as  $e_1 \times e_2 = e_3$ ,  $e_2 \times e_3 = e_1$ ,  $e_3 \times e_1 = e_2$  and extended linearly and skew-symmetrically forms a Lie algebra. This is denoted as  $\mathfrak{so}(3)$ .
2. Given the  $n \times n$  matrices  $\text{Mat}_{n \times n}(\mathbb{R})$ , then

$$[A, B] := A \circ B - B \circ A$$

for  $A, B \in \text{Mat}_{n \times n}(\mathbb{R})$  and  $\circ$  the matrix multiplication, forms a Lie algebra denoted as  $\mathfrak{gl}_n(\mathbb{R})$ .

3. The classical Lie algebras  $\mathfrak{o}(n) = \mathfrak{so}(n)$ ,  $\mathfrak{u}(n)$ ,  $\mathfrak{su}(n)$ ,  $\mathfrak{sp}(n)$ ,  $\mathfrak{sl}_n(\mathbb{R})$  are ...



# Formulating proofs

1. State what you need to prove,
2. prove it,
3. say that you have proved it.
  - Make it read smoothly.





## Example: Proof

### Proof.

We want to show that  $\mathfrak{gl}_n(\mathbb{R})$  is indeed a Lie algebra. The bracket is bilinear, because matrix multiplication is. By inspection the bracket also is skew-symmetric. It remains to show the Jacobi identity. We will start with the well-known fact that matrix multiplication is associative, i.e.  $(A \circ B) \circ C = A \circ (B \circ C)$  for every  $A, B, C \in \mathfrak{gl}_n(\mathbb{R})$ . We can therefore avoid parentheses in the following computation

$$\begin{aligned} [A, [B, C]] &= [A, B \circ C - C \circ B] \\ &= A \circ B \circ C - A \circ C \circ B - B \circ C \circ A + C \circ B \circ A. \end{aligned}$$

Cyclic permutation of  $A$ ,  $B$ , and  $C$  leads to

$$\begin{aligned} [B, [C, A]] &= B \circ C \circ A - B \circ A \circ C - C \circ A \circ B + A \circ C \circ B, \\ [C, [A, B]] &= C \circ A \circ B - C \circ B \circ A - A \circ B \circ C + B \circ A \circ C. \end{aligned}$$

Adding up the three equations leads to the Jacobi identity. This completes the proof. □



## Putting things together

### Book

1. Name some chapters,
2. write them one by one, going back to add / change whenever necessary,
3. proof read and rearrange,
4. write the introduction

### Article

1. Start with the statement of the main theorem(s),
2. state a main definition,
3. write the proof and add definitions and lemmas as required,
4. give examples
5. proof-read
6. write the introduction



## Formulating an introduction

1. Search for more related literature;
2. Explain where the main definition is used in your area;
3. avoid formulas – this is not the main body of the paper;
4. Explain the meaning of your main theorem, implications, interpretation;
5. Relate to other people's research (earlier results, conjectures, the big picture);

optional give outlook on further related questions.

7. contents of each section



# Style

- Things to avoid
- emotional adjectives: excellent, good, nice, bad, awful, important, . . . ;
  - long complicated sentences;
  - imprecise formulation;
  - grammar mistakes

- Helpful
- + use math terms properly;
  - + consistent use of symbols;
  - + reused examples;



## Where to put conclusions

Out of 10000 active mathematicians so many read the following of an important paper:

3000	title,
1000	abstract,
300	introduction,
250	statement of main theorem,
250	some preliminaries,
50	proof

Therefore, in most math papers conclusions are put in the middle / at the end of the introduction or as corollaries after the main theorem.



# Writing an abstract

1. Summarize the main theorem(s) in one sentence each.
2. avoid math symbols;
3. only 1–2 short paragraphs



# Choosing a title

- informative,
- short,
- honest
- “On Courant algebroids”
- + “Structure of regular Courant algebroids”



## Further reading

- math literature in your field
- good math lectures
- P.R. HALMOS: *How to write math.* in L'Enseignement Mathématique, vol. 16 (**1970**).  
[www.math.uga.edu/~azoff/courses/halmos.pdf](http://www.math.uga.edu/~azoff/courses/halmos.pdf)





## Next: More about writing math

- good / bad formulations
- some mathematical notions

